

Annihilation of charged particles

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The kinetics of irreversible annihilation of charged particles performing overdamped motion induced by long-range interaction force, $F(r) \sim r^{-\lambda}$, is investigated. The system exhibits rich kinetic behaviors depending on the force exponent λ . In one dimension we find that the densities decay as $t^{-1/(2+\lambda)}$ and $t^{-1/(1+2\lambda)}$ when $\lambda > 1$ and $1/2 < \lambda < 1$, respectively, with logarithmic correction at $\lambda = 1$. For $\lambda \leq 1/2$, the asymptotic behavior is shown to be dependent on system size.

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I. INTRODUCTION

The kinetics of two-species diffusion-controlled annihilation reaction, $A + B \rightarrow 0$, between *uncharged* particles has been a subject of extensive research for almost 20 years [1]. For sufficiently low spatial dimension, $d < 4$, even under homogeneous initial conditions, large-scale heterogeneities arise that invalidate classical kinetic laws. Much less is known about annihilation reaction between *charged* particles with long-range power-law interaction, $F(r) \sim r^{-\lambda}$. An important case of Coulomb interaction ($\lambda = d - 1$ in d dimensions) has been treated in a few studies [2–5] for $d = 2$ and 3. However, some of these works were based on unjustified approximations while others were based solely on numerical simulations, so their results are also uncertain. (Note that even for pure annihilation of uncharged particles in three dimensions the asymptotic regime is hardly reached on modern computers.) Moreover, competing results have appeared in the literature; e.g., for the Coulomb systems, the classical decay of concentration, $n \sim t^{-1}$, has been advocated in [2,3] in all dimensions, while Ref. [5] has argued for a slower decay, $n \sim t^{-6/7}$, in two dimensions. We, therefore, see that even the Coulomb case still deserves further investigation. Other values of the interaction exponent λ also naturally appear in applications with particles being dipoles, defects, vortices, monopoles, disclinations, etc. One important example is the quench of a one-dimensional Ising system from a disordered state to an ordered state. If spins interact via long-range potential [6], the Hamiltonian may be expressed in terms of interacting domain walls [7]. There are two types of domain walls in the system, the domain walls with “up” spins to the right and “down” to the left (A walls), and *vice versa* (B walls). Thus, the spin chain is represented by an alternating domain wall sequence $\dots ABABAB\dots$. Domain walls annihilate upon colliding, $A + B \rightarrow 0$, but since the alternating structure persists in time, the reaction process is, in fact, equivalent to the single-species annihilation, $D + D \rightarrow 0$. This system has been recently investigated [7–9], and it was shown that particle concentration decays as $t^{-1/(1+\lambda)}$.

In this paper we consider a truly two-species annihilation model where the initial distribution of interacting particles

(“charges”) is random (Poissonian). The forces between charges are assumed to be proportional to $r^{-\lambda}$, with similar charges repelling each other and dissimilar attracting each other. Compared to the single-species case, the two-species annihilation exhibits more rich kinetic behavior including the dependence on the system size. In this study we focus on one-dimensional (1D) systems that allow us to find rather convincing numerical support for our scaling predictions.

The paper has the following structure: In the next section we formally introduce the model, an ensemble of interacting particles in one dimension with overdamped dynamics. Then, relying on heuristic arguments, we obtain density decay exponents for $\lambda > 0$ (peculiarities of the 1D Coulomb system, $\lambda = 0$, are addressed in Appendix A). In Sec. III, we present the results of numerical simulations. Finally, in Sec. IV we discuss possible generalizations of the model including higher dimensionality and ballistic motion, and make general conclusions.

II. THE MODEL AND SCALING ARGUMENTS

We consider two-species systems containing A - and B -type particles with charges $+1$ and -1 for “particles” and “antiparticles,” respectively. Particles of both species move continuously on a one-dimensional line and interact via long-range force: $F = qq'/r^\lambda$ for charges q and q' separated by the distance r . Initially, A - and B -type particles are randomly distributed with equal concentrations; for simplicity we put the concentrations equal to 1.

Total force acting on the i th particle is equal to a sum of pairwise forces:

$$F_i = q_i \sum_{j \neq i} \frac{q_j (x_i - x_j)}{|x_i - x_j|^{\lambda+1}}, \quad (1)$$

where $q_k = \pm 1$ and x_k are charge and coordinate of the k th particle. We will ignore particle inertia, i.e., motion of particles is assumed to be overdamped. Therefore, the velocity of each particle v_i is proportional to the total force F_i acting on it, $v_i = \mu F_i$. (In the following, we set the mobility μ equal to 1.) We will also ignore particle diffusion; that is, we will assume that the drift dominates the random walk effects. When two dissimilar particles collide, both of them irreversibly disappear; collisions between particles of the same species are impossible because of repulsion. To summarize, we

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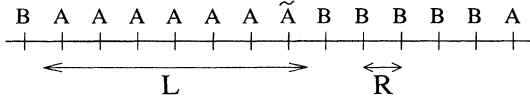


FIG. 1. Schematic illustration of domain structure. Typical domain has length L and consists of $M=6$ particles; average distance between particles is $R=L/N$.

consider two-species annihilation of particles undergoing overdamped noiseless motion. We will see that for a sufficiently large force exponent ($\lambda > 4$ in one dimension), the noise actually dominates the drift, and thus well-known diffusion-controlled kinetic behavior [1] emerges. However, for small λ , we expect that the long-time behavior is correctly described by our noiseless model. We will also briefly discuss a model where the motion is ballistic (Sec. V).

Let us now consider time evolution of the system. We cannot *a priori* expect that a mean-field description holds in low dimensions, especially in one dimension. Remember that the breakdown of the mean-field behavior in reaction-diffusion models is generally attributed to the formation of single-species domains [1]. We assume that the same takes place in our model; at least in one dimension, the formation of domains is inevitable.

Suppose that at time t the length of a typical single-species domain is $L(t)$. It means that an average number of particles in such a domain is equal to initial imbalance of majority and minority species on the length $L(t)$, which for Poissonian initial distribution with the density one is of the order of $\sqrt{L(t)}$. Therefore, the concentration $n(t)$ in a typical domain behaves as

$$n(t) \sim 1/\sqrt{L(t)}. \quad (2)$$

To get an insight into how a typical domain length changes in time, we consider motion of a single particle \tilde{A} on a domain edge (Fig. 1). Here we assume that the system is entirely formed of well-defined domains of typical length L . The total force acting on \tilde{A} from the particles on its left may be evaluated as

$$F \sim \sum_{j=1}^M \frac{1}{x_j^\lambda} - \sum_{j=1}^M \frac{1}{(x_j+L)^\lambda} + \sum_{j=1}^M \frac{1}{(x_j+2L)^\lambda} - \dots \quad (3)$$

Here M is a typical number of particles in a domain, $M \sim \sqrt{L}$. Each sum on the left-hand side of Eq. (3) expresses a contribution to the net force from a particular domain; to get the total force these contributions have been added. It is clear that the force exerted on \tilde{A} from all the particles to the right may be calculated in exactly the same way. To simplify the matter even further we assume that $x_j \approx R \times j$, where R is an average interparticle separation; $R = L/M$. Rewriting Eq. (3) through R and M gives

$$F \sim \frac{1}{R^\lambda} \left[\sum_{j=1}^M \frac{1}{j^\lambda} - \sum_{j=1}^M \frac{1}{(j+M)^\lambda} + \sum_{j=1}^M \frac{1}{(j+2M)^\lambda} - \dots \right]. \quad (4)$$

Depending on the value of the force exponent λ , different situations appear. For $\lambda > 1$, the first sum converges to a finite

value for $M \rightarrow \infty$ while the other sums approach zero as $M^{-(\lambda-1)}$, which means that only charges from the left and right nearest neighbor domains essentially contribute to the total force. For $0 < \lambda < 1$, all sums diverge as $M^{1-\lambda}$ as $M \rightarrow \infty$. The total force, being the sum of monotonically decreasing sign-alternating terms, is of order of the contribution of the first domain. In the borderline case $\lambda = 1$, the first sum diverges as $\log M$ while the other terms are monotonically decreasing, sign alternating, and finite. The dominate contribution is again provided by the nearest domains. To sum up,

$$F \sim \frac{1}{R^\lambda} \times \begin{cases} M^{1-\lambda} & \text{if } 0 < \lambda < 1 \\ \log M & \text{if } \lambda = 1 \\ 1 & \text{if } \lambda > 1. \end{cases} \quad (5)$$

On the other hand, a typical rate of change of the domain length is of order of the velocity of any of its edges. Recalling that $R \sim M \sim \sqrt{L}$, we obtain

$$dL/dt \sim F \sim \begin{cases} L^{1/2-\lambda} & \text{if } 0 < \lambda < 1 \\ L^{-1/2} \log L & \text{if } \lambda = 1 \\ L^{-\lambda/2} & \text{if } \lambda > 1. \end{cases} \quad (6)$$

Solving (6) for $L(t)$ and using relation (2), we finally write for the density decay asymptotics:

$$n(t) \sim \begin{cases} t^{-1/(1+2\lambda)} & \text{if } 0 < \lambda < 1 \\ (t \log t)^{-1/3} & \text{if } \lambda = 1 \\ t^{-1/(2+\lambda)} & \text{if } \lambda > 1. \end{cases} \quad (7)$$

These results are, in fact, correct only for $1/2 \leq \lambda \leq 2$. The upper bound follows from comparison of the random walk length, $L_{RW} \sim t^{1/2}$, with the drift length, $L \sim t^{2/(2+\lambda)}$ when $\lambda > 1$. For $\lambda > 2$, $L_{RW} \gg L$, so a pair of charges can escape annihilation through a random walk, and therefore the diffusion controls the dynamics. Thus, for $\lambda > 2$, the diffusion-controlled asymptotic behavior, $n \sim t^{-1/4}$, is expected. The lower bound, $\lambda = 1/2$, stems from the fact that an average force acting on any particle in the *infinite-particle* 1D system becomes infinite for $\lambda \leq 1/2$. It can be shown rigorously by deriving a Holtsmark-like [10] force distribution (this is detailed in Appendix B). Here, we provide more qualitative arguments that take into account the finiteness of the system. First, we note that the calculation of the total force (3) has implicitly assumed that the system is perfectly ordered—it consists of similar domains of A and B particles; i.e., the total charge of the first domain is equal, up to the sign, to the total charge of the second domain, etc. In particular, it means that for a system depicted in Fig. 1, the overall charge to the left of the test particle \tilde{A} is -1 , and the overall charge to the right is zero. However, this picture is a “mean field” in spirit; hence, it can lead to erroneous results for truly random systems. Fluctuations in initial charge distribution in the system with N particles produce the net charge of the order \sqrt{N} to the left and to the right of the test particle. Qualitatively, we can estimate the effect of charge imbalance by putting \sqrt{N} equidistant charges of one sign to the right and the same amount of the opposite charges to the left. (When we consider *finite* systems of charges we implicitly assume that they satisfy the neutrality condition; generally, the total

net charge determines the long-time behavior.) The initial size of the system is N , so the distance between nearest charges left in the system is \sqrt{N} ; thus, the force F_N due to the charge imbalance is

$$F_N \sim \frac{1}{N^{\lambda/2}} \sum_{j=1}^{\sqrt{N}} \frac{1}{j^\lambda} \sim N^{-\lambda+1/2}. \quad (8)$$

While $F_N \rightarrow 0$ as $N \rightarrow \infty$, this force does not affect the dynamics of the model. Thus, for $\lambda > 1/2$ our previous estimate, $F \sim L^{1/2-\lambda}$, gives the dominant contribution, and the size-independent dynamics [7] emerges. However, for $\lambda < 1/2$ the total force acting on a particle grows with system size even for overall neutral systems; therefore, it should dominate over the “regular” force (3) and control the dynamics of the system. It seems reasonable to assume that at the early stages of time evolution, when the distribution of the particles is still almost random, the motion of domain edges is controlled by the force (8). Repeating the steps used in deriving Eq. (7), with $F \sim N^{1/2-\lambda}$ instead of Eq. (6), we obtain for the density decay

$$n(t) \sim N^{(2\lambda-1)/4} t^{-1/2}. \quad (9)$$

However, this estimate may become inapplicable on the later stages of evolution. Indeed, the dynamics described by Eq. (9) is extremely fast since it is size dependent, so the charge distribution that emerges can be significantly different from the Poissonian; as a result, our assumption about the type of randomness of the particle distribution could become less and less appropriate.

III. SIMULATION RESULTS

To check our heuristic predictions, we have performed numerical simulations for $\lambda=1, 0.75, 0.5, 0.25$, and 0 (the Coulomb case $\lambda=0$ turns out to be special; it will be discussed separately in Appendix A). Our system initially consisted of 10 000 particles of each species randomly distributed with concentration 1. First, the net force (1) is calculated for each particle. We compute all the forces directly without applying any multipolelike expansion that could be useful in many dimensions [12]. With the particle velocity equal to the total force, we employ a simple Euler update procedure for each time step: $\Delta x_i = F_i \Delta t$. The selection of time interval Δt was merely experimental. Since on the last stages of evolution simulations run very fast (few particles are left), we, unlike Refs. [7] and [8], keep Δt constant during a run. Finally the results are averaged over 10 runs. The selection of boundary conditions does not seem to affect the results of simulations of the two-component system with overall neutrality, except for, maybe, its latest stages. We ran the simulations for $\lambda=0.25$ with both periodic and open boundary conditions; the results for concentration coincided within a statistical error. Hence, we use open boundary conditions for all further simulations.

In Fig. 2 we plot, for various λ , the concentration of either species versus time. As we anticipated, for $1/2 < \lambda$ our predictions for the decay of concentration are in good agreement with the results of simulation. Indeed, the average slope of the $\log[n(t)]$ versus $\log t$ plot for $\lambda=1$ is -0.322 [the heu-

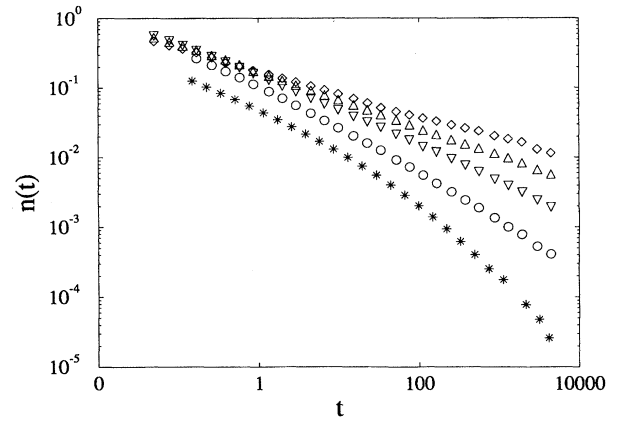


FIG. 2. Plot of concentration $n(t)$ vs time on a double logarithmic scale (arbitrary units) for $\lambda=1$ (\diamond), $\lambda=3/4$ (\triangle), $\lambda=1/2$ (∇), $\lambda=1/4$ (\circ), and $\lambda=0$ ($*$).

ristic argument gives $(t \log t)^{-1/3}$], and -0.401 (compared to $-2/5$) for $\lambda=3/4$. Performing numerical simulations with a twice smaller system (5000 pairs of particles), we did not find any significant system size dependence for these values of λ . As for $\lambda \leq 1/2$, no power-law behavior can be observed for density decay. However, at the early stages of evolution, local exponents are close to $-1/2$ as follows from Eq. (9); as time goes on, the density decay rate increases.

IV. DISCUSSION

Considering the dynamics of domain interfaces and using simple heuristic arguments, we have predicted the asymptotic density decay in a two-species annihilation reaction system with long-range interaction and overdamped motion. In principle, this approach can be generalized on similar systems in an arbitrary spatial dimension d . We assume that in the asymptotic regime the system still consists of well-defined domains of opposite species, and analyze the dynamics of interfaces as we did in Sec. II for the 1D case. First, we relate the concentration $n(t)$ to the typical domain size $L(t)$ by a straightforward generalization of Eq. (2), $n \sim 1/\sqrt{L^d}$. Then, we estimate a force exerted on a particle near an interface and obtain a generalization of Eq. (3), with typical terms like $R^{-\lambda} \sum_{j \leq M} j^{d-1}/j^\lambda$. Here R is an average interparticle distance and M^d is an average number of particles in a domain, $R \sim M \sim \sqrt{L}$ as previously. For $\lambda > d$ the neighboring particles provide the dominant contribution to the force, i.e., $F \sim R^{-\lambda} \sim L^{-\lambda/2}$. On the other hand, for $\lambda < d$ all particles from the neighboring domains should be taken into account, and we obtain $F \sim M^{d-\lambda} R^{-\lambda} \sim L^{-\lambda+d/2}$. In the borderline case of $\lambda=d$, a logarithmic correction appears, $F \sim L^{-d/2} \log(L)$. Substituting these estimates into $\dot{L} = F$, we solve for the size L , and get for the concentration:

$$n(t) \sim \begin{cases} t^{-d/(2-d+2\lambda)} & \text{if } d/2 \leq \lambda < d \\ (t \log t)^{-d/(2+d)} & \text{if } \lambda = d \\ t^{-d/(2+\lambda)} & \text{if } \lambda > d. \end{cases} \quad (10)$$

For $\lambda < d/2$, we expect size-dependent kinetics. This assertion is justified in Appendix B.

As in the 1D case, let us compare the typical domain size L and the diffusion length scale, $L_{RW} \sim t^{1/2}$. We see that for $\lambda > d$ the random walk dominates over the drift, and diffusion-controlled behavior is expected. Thus, the regime described by the lower line of Eq. (10) does not appear for $d \geq 2$; instead, the correct behavior is provided by the diffusion-controlled decay of the system of *noninteracting* particles [1], i.e., $n \sim t^{-d/4}$ for $d < 4$ and $n \sim t^{-1}$ for $d \geq 4$.

Note that for truly Coulomb systems, $\lambda = d - 1$, the scaling prediction of Eq. (10) is $n \sim t^{-1}$; i.e., the classical kinetic law. This is expected to hold when $d/2 \leq \lambda = d - 1 \leq 2$, i.e., $2 \leq d \leq 3$. For $d < 2$, size-dependent kinetics is anticipated; while for $d > 3$, the Coulomb interaction becomes irrelevant and the diffusion-controlled behavior emerges. Another interesting example is the system of D -dimensional Coulomb charges confined to the $D - 1$ hypersurface. In this case the force exponent $\lambda = D - 1$ is equal to the dimension of the hypersurface $d = D - 1$ and Eq. (10) predicts a logarithmically corrected power-law behavior, $n \sim (t \log t)^{-(D-1)/(D+1)}$.

However, it is not clear whether the concept of unpenetrable (untransparent) domains with continuous boundaries is still applicable for $d > 1$. Competition between screening, which makes long-range interaction effectively short ranged, and annihilation may also significantly affect the behavior of the system. We attempted to simulate a 2D system on a lattice. Either because of the large effective diffusion, which is inevitably introduced by the discrete nature of the lattice model, or for some deeper reason, we were unable to observe any scalinglike behavior. Since many-dimensional continuous many-body simulations are still computationally challenging, we leave this problem for the future.

More can probably be done with one-dimensional systems as well. One can try to find exact results for some specific values of the force exponent λ . For the Coulomb system, $\lambda = 0$, we indeed succeeded in finding some properties analytically (see Appendix A and Ref. [11]), but we still could not find a complete solution. Another extreme case, $\lambda \rightarrow \infty$, is also theoretically challenging. (In fact, the diffusion determines the dynamics for $\lambda > 4$ so one should consider a *strictly* noiseless system.) The dynamics in the $\lambda \rightarrow \infty$ limit is extremal: One picks the pair of nearest neighbors that are *closest* to each other and removes it if the charges are dissimilar, or recedes them if the charges are similar. The receding is stopped when the distance reaches the second minimal interchange distance. Then, if this second closest pair contains dissimilar charges, it is removed while the first pair continues receding; if the second pair is also the same species, both pairs recede. If the initial sequence is alternating as it takes place with domain walls in the quench process, one always removes the closest pairs, and the domain-size distribution function approaches the scaling form. This model turns out to be completely solvable [8,13–15]. It would be very interesting to study a more complex version of the extremal dynamics that arises from the present two-species annihilation process.

Finally, we discuss a model where motion of the particles is ballistic; i.e., it is described by Newton's laws. We again focus on the one-dimensional situation. It is clear enough that the only change one needs to make in the above ap-

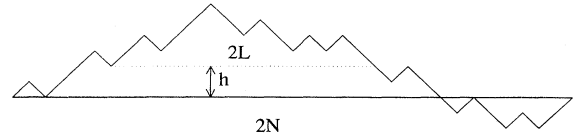


FIG. 3. RW representation of a two-species neutral system. Number of particles of each species, $N = 17$. A neutral segment of the length $2L = 16$ is shown having $h = 2$ uncompensated charges to the left and to the right of it.

proach is to put $d^2 L / dt^2$ instead of dL / dt into the left-hand side of Eq. (6). Assuming that initial velocities are irrelevant, we obtain for the concentration

$$n(t) \sim \begin{cases} N^{(2\lambda-1)/4} t^{-1} & \text{if } \lambda < 1/2 \\ t^{-2/(1+2\lambda)} & \text{if } 1/2 < \lambda < 1 \\ (t \log t)^{-2/3} & \text{if } \lambda = 1 \\ t^{-2/(2+\lambda)} & \text{if } 1 < \lambda < 2 \\ t^{-1/2} & \text{if } \lambda \geq 2. \end{cases} \quad (11)$$

When $\lambda \geq 2$, the inertia dominates the drift and, therefore, the ballistic-controlled asymptotic behavior [16], given by the last line of Eq. (11), follows.

Numerical simulations performed for $\lambda = 0.75$ showed that the concentration decays as $t^{-0.79}$ compared to $t^{-4/5}$ as follows from Eq. (11).

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APPENDIX A: $\lambda = 0$

The $\lambda = 0$ case, corresponding to the truly 1D Coulomb system, has several peculiar features. Since the forces between particles do not depend on the distance, and particles disappear in pairs, the net force acting on a particle is constant throughout its life. It means that velocity of any particle is constant and equal to the difference between total charge to the left and total charge to the right of it multiplied by a charge of the particle. Taking into account that initial distribution of particles is Poissonian, one can easily describe the behavior of the system if the probability distribution for “charge imbalance” were known. To get an insight about this charge imbalance distribution, we look at our configuration of charges as on a 1D random walk (RW) (Fig. 3). Step up corresponds to a positive charge, step down to the negative; since the system is neutral overall, the RW returns to the origin after $2N$ (the size of the system) steps. The net force acting on a particle is equal to the “height” h , positive or negative, of the corresponding point in the RW picture. The joint distribution function $W_{2N}(h, 2L)$ tells us how many segments (loops in the RW terminology) of the length $2L$, starting and ending at the “height” h from the origin, exist in a RW coming to the origin (not necessarily for the first time) after $2N$ steps. Knowing this function, one can readily cal-

culate a life expectation time for each particle, and therefore the concentration decay rate:

$$\frac{dn}{dt} = -\frac{1}{\tilde{L}} \sum_{L=0}^N \sum_{h=0}^{N-L} W_{2N}(h, 2L) P_{2L}[2t(2h+1)]. \quad (\text{A1})$$

Here \tilde{L} is initial system length and $P_j(x) = x^j e^{-x}/j!$ the Poisson distribution function. So far we have been able to determine another function, $\tilde{W}_{2N}(2L)$, which gives the probability that the *maximum* length of the “zero-height” segment in a system with $2N$ charges is $2L$ [11]. This maximum length segment determines the lifetime of the whole system, which is shown to be proportional to its size $2N$. Moreover, the lifetime distribution function has a remarkably rich structure (an infinite set of singularities, etc.; see [11]).

Although we were not able to find the exact expression for the decay of concentration in this case, numerical simulations of this problem prove to be very simple. Instead of running a molecular dynamics algorithm, it is sufficient to calculate all the net forces once and find an annihilation partner for each particle; after that, we know the lifetimes for all the particles in the system. It enabled us to check an accuracy of our molecular dynamics simulation for our standard (10^4 pairs) system size and also to study the systems with up to 10^5 particles of each species. Even for these relatively big systems, we were unable to find any power-law behavior; the function that fits best our simulation results looks like $n(t) \sim \exp(-0.05 \log^4 t)$.

APPENDIX B: TYPICAL FORCE IN A SYSTEM OF CHARGED PARTICLES

A problem of distribution of a typical force in a system of particles with Coulomb interaction was first studied by Holtmark [10]. Using the same approach, we will show that for arbitrary dimensionality and $r^{-\lambda}$ interaction, the typical (or mean) force is finite in an infinite system only for some range of the force constants λ , specifically for $\lambda > d/2$. We start from an expression for the force distribution function $W(\vec{F})$, which gives the probability that the force, acting on a “test particle,” which we will put at the origin, is equal to F :

$$W(\vec{F}) = \left\langle \delta \left(\vec{F} - \sum_{j=1}^N \vec{f}(\vec{r}_j) \right) \right\rangle_{\text{av}}, \quad (\text{B1})$$

where $\vec{f}(\vec{r}_j) = \vec{r}_j / r_j^{\lambda+1}$ is the force exerted by a j th particle on the test one. Since we assume that spatial distribution of particles is random and independent, it is sufficient to consider a one-component system. Replacing the δ function by auxiliary integration over $d\vec{k}$ we obtain

$$W(\vec{F}) = \frac{1}{(2\pi)^d} \int \exp(i\vec{k} \cdot \vec{F}) S(\vec{k}) d\vec{k}, \quad (\text{B2})$$

with

$$\begin{aligned} S(\vec{k}) &= \int \cdots \int \exp \left(- \sum_{j=1}^N i\vec{k} \cdot \vec{f}(\vec{r}_j) \right) \prod_{j=1}^N \frac{d\vec{r}_j}{V} \\ &\equiv \left(\frac{1}{V} \int e^{-i\vec{k} \cdot \vec{f}} d\vec{r} \right)^N. \end{aligned} \quad (\text{B3})$$

Here $\vec{f} = \vec{r}/r^{\lambda+1}$, N is the number of particles in the system, and V is the volume. Rewriting (B3) in the form

$$S(\vec{k}) = \left[1 - \frac{1}{V} \int (1 - e^{-i\vec{k} \cdot \vec{f}}) d\vec{r} \right]^N, \quad (\text{B4})$$

and taking the thermodynamic limit, $N \rightarrow \infty$ and $V \rightarrow \infty$ where $N/V = n$ is kept fixed, yields

$$S(\vec{k}) = \exp \left(-n \int [1 - e^{-i\vec{k} \cdot \vec{r}/r^{\lambda+1}}] d\vec{r} \right). \quad (\text{B5})$$

After expanding the exponent in the integrand for large r and performing angular integration (which eliminates all odd-order terms) one finds that for system size $R \rightarrow \infty$, the integral in the left-hand side of Eq. (B5) converges only if $\lambda > d/2$ while for $\lambda < d/2$ the integral diverges with the system size. More precisely, a considerable but straightforward computation yields

$$S(\vec{k}) \equiv S(k) = \exp[-n\Omega_d A(d, \lambda) k^{d/\lambda}] \quad (\text{B6})$$

for $\lambda > d/2$. In Eq. (B6), $\Omega_d = 2\pi^{d/2}/\Gamma(d/2)$ denotes the surface area of the unit sphere in d dimensions and $A(d, \lambda)$ is the shorthand notation for the integral

$$A(d, \lambda) = \int_0^\infty \frac{dz}{\lambda z^{d/\lambda+1}} \left[1 - \Gamma \left(\frac{d}{2} \right) \left(\frac{2}{z} \right)^{d/2-1} J_{d/2-1}(z) \right],$$

with $\Gamma(z)$ being the Euler Γ function, and $J_\nu(z)$ the Bessel function. For $\lambda < d/2$ the integral in the right-hand side of Eq. (B5) grows as $[2\Omega_d/d(d-2\lambda)]R^{d-2\lambda}k^2$. Returning back to Eq. (B2) we see that in the case of ($\lambda \leq d/2$) the net force is given by

$$W(\vec{F}) = \frac{1}{(2\pi)^d} \int \exp \left(i\vec{k} \cdot \vec{F} - \frac{2\Omega_d}{d(d-2\lambda)} R^{d-2\lambda} k^2 \right) d\vec{k}. \quad (\text{B7})$$

In the limit $R \rightarrow \infty$, we compute the integral in Eq. (B7) asymptotically to find

$$\begin{aligned} W(\vec{F}) &\sim [(d-2\lambda)R^{2\lambda-d}F]^{d-1} \\ &\times \exp[-\text{const}(d-2\lambda)R^{2\lambda-d}F^2]. \end{aligned} \quad (\text{B8})$$

Equations (B7) and (B8) are valid for $\lambda < d/2$. For $\lambda = d/2$, $R^{d-2\lambda}/(d-2\lambda)$ should be replaced by $\log R$. For $d=1$ and $R \propto N$, the net force has the Gaussian distribution, $W(\vec{F}) \propto (1-2\lambda)^{1/2} N^{\lambda-1/2} \exp[-(1-2\lambda)N^{2\lambda-1}F^2]$, and therefore the typical force grows with size as $N^{1/2-\lambda}$ in agreement with qualitative results of Sec. II. Note also that for $\lambda=1/2$ the typical force still grows with system size, $F \sim \sqrt{\log N}$, and hence the density decay of the form $n(t) \sim (\log N)^{-1/d} t^{-1/2}$ is expected.

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